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# Classical Mechanics By G Aruldas Pdf



½ The solved problems of classical mechanics are included in the universal constant  $G$ , which is already present in (1) and (2). That is, we can put  $m_P = m_A$ . Note that if we set  $m_P = m_A = m_M$ , then we get equation (5), so we need to solve (5), which can also be written in the form [5], or, in other words, where  $G$  is a universal constant, a coefficient of proportionality. It follows from (4.1) and (4.2) that  $G$  is a quadratic function. Note also that  $g$ , as shown earlier, is positive (or negative), that is, it makes sense only for positive  $a$ , so in what follows we will assume that  $g$  is positive.

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